

Black Holes & Neutron Stars in Tensor-Vector-Scalar Theory

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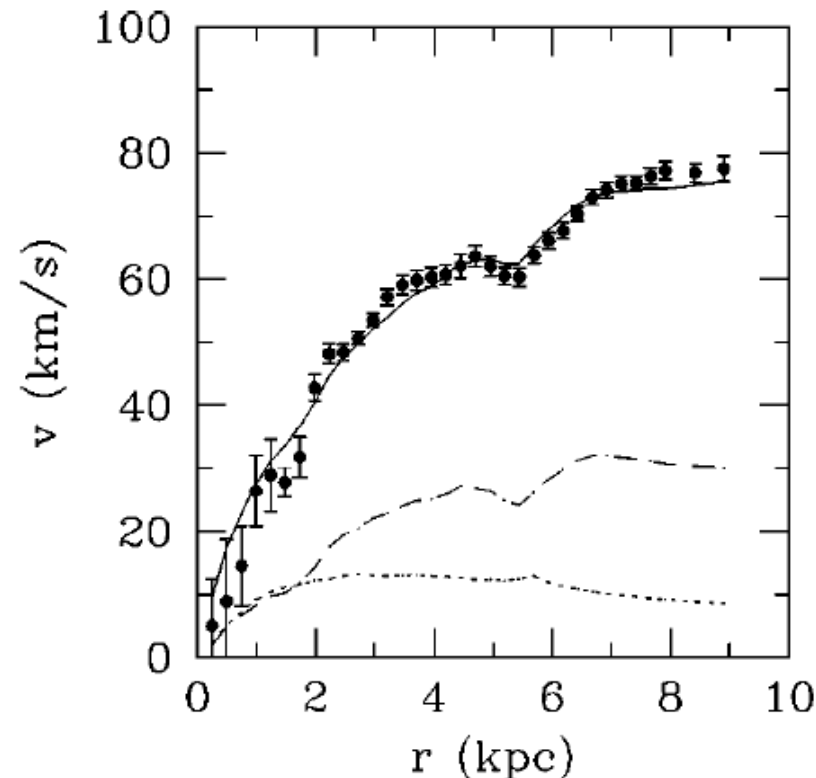


Modified Newtonian Dynamics (MoND)

Milgrom (1983); Bekenstein & Milgrom (1984)

Phenomenologically based on observations of spiral galaxies:

- 1) Asymptotically flat rotation curves
- 2) Tully-Fisher law (relationship between rotation velocity & luminosity in spiral galaxies)



$$\mu(|\mathbf{a}|/a_0) \mathbf{a} = -\nabla \Phi_N$$

$$\mu(x) = \begin{cases} x & \text{for } x \ll 1 \\ 1 & \text{for } x \gg 1 \end{cases}$$

**has been argued to be
“better” than CDM**

- 1) more predictive than CDM
- 2) more easily falsifiable (only one parameter)

Modified Newtonian Dynamics (MoND)

Milgrom (1983); Bekenstein & Milgrom (1984)

Not a covariant theory;

**Good as a toy-model... need
relativistic theory**



Bekenstein (2004)

**“Relativistic gravitation theory for the
modified Newtonian dynamics paradigm”**

**Tensor-Vector-Scalar theory
(TeVeS)**

Bekenstein's TeVeS Theory

Bekenstein (2004) - Relativistic version of MoND

Weak Acceleration Limit

TeVSe = MoND

Cosmological Scales

**Strong Lensing
LSS, CMB**

Newtonian Limit

Parametrized Post-Newtonian (PPN)
coefficients agree with all solar
system tests.

**What can we learn about TeVeS in
strong gravitational fields?**

But first, we need to understand more about the theory

A TeVeS Primer

TeVeS = **Tensor** - **Vector** - **Scalar**

$$S_{\text{tot}} = S_g + \mathcal{K} S_v + k S_s + S_{\text{mat}}$$

**Vector-field Coupling
Constant (i.e. strength
of the vector field)**

**Scalar-field Coupling
Constant (i.e. strength
of the scalar field)**

Scalar field ==> extra potential to gravitational field

Vector field ==> required light bending properties

Reduces to GR when

$$\mathcal{K} = k = 0$$

A TeVeS Primer

Tensor, vector and scalar fields combine to
give physical metric...

Clocks & Rulers measured by physical metric

$$\tilde{g}_{\mu\nu} = e^{-2\varphi} (g_{\mu\nu} + \mathcal{U}_\mu \mathcal{U}_\nu) - e^{2\varphi} \mathcal{U}_\mu \mathcal{U}_\nu$$

Stretch Einstein metric in directions **orthogonal**
Shrink **parallel** to \mathcal{U}^μ by $e^{-2\varphi}$

put in “by hand” to make sure
extra lensing is required in
accordance with observations

Solving TeVeS field equations in Strong-Field regime



Giannios (2005)

:- “Schwarzschild” solution

Sagi & Bekenstein (2008)

:- “Reisner-Nordstrom”

**PL, Sotani & Giannios (2008) :- “TOV” solution for perfect fluid
i.e. neutron star models**

**Using observations of neutron star masses,
we put constraints on \mathcal{K} and φ_c .**

And THEN.....

Seifert (2007):- Schwarzschild-TeV S unstable

Contaldi et al. (2008):- Evolving vector field causes caustics

Sagi (2009):- Superluminal propagation of scalar waves

**Conclusion: original TeV S theory
does not work!!**

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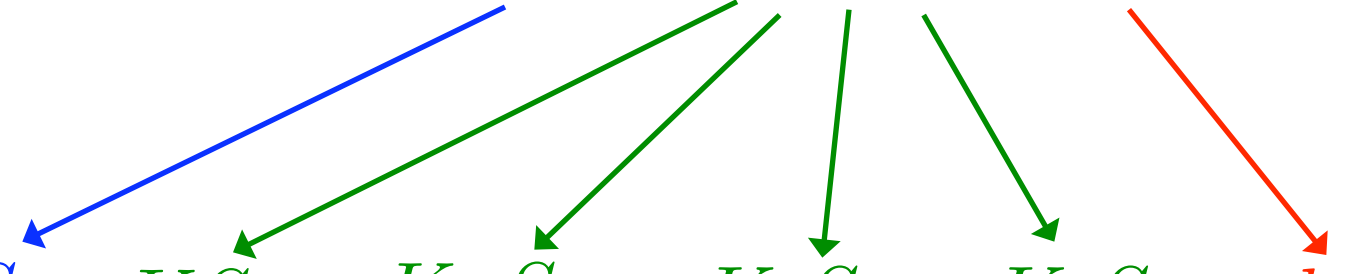
Skordis (2008), Contaldi et al. (2008) & Sagi (2009)

“Generalized-TeV_S”

**Fixes aforementioned problems by allowing for more
general dynamics of the vector field**

A Generalized TeVeS Primer

TeV**S** = **Tensor** - **Vector** - **Scalar**



$$S_{\text{tot}} = S_g + K S_K + K_+ S_{K_+} + K_2 S_{K_2} + K_4 S_{K_4} + k S_s + S_{\text{mat}}$$

“... most general kinetic term for A, which is diffeomorphism invariant, quadratic in derivatives and ... consistent with $A^2 = -1$ constraint”*

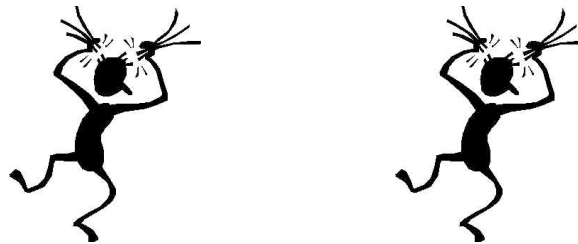
Reduces to original TeVeS when

$$K_+ = K_2 = K_4 = 0$$

* Contaldi et al. (2008)

Solving Generalized-TeVS field equations

PL (2009) :- Schwarzschild solution
:- Reisner-Nordstrom solution
:- TOV (i.e. neutron stars)



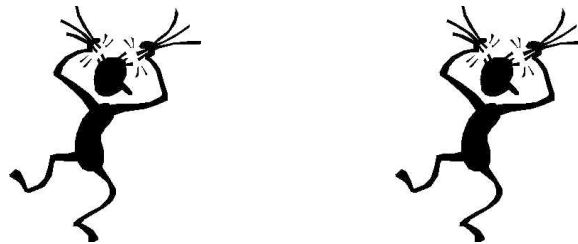
1) Can only measure one certain combination of vector-field coupling constants using static, spherically symmetric spacetimes.

2) BHs and NSs look **EXACTLY** the same in TeVeS and Gen-TeV S (providing only using EM radiation);

$$K_2 = 0 \quad \& \quad K + K_+ - K_4 = \mathcal{K}$$

Solving Generalized-TeVS field equations

PL (2009) :- Schwarzschild solution
:- Reisner-Nordstrom solution
:- TOV (i.e. neutron stars)



3) All results of Giannios (2005), Sagi & Bekenstein (2008), PL, Sotani & Giannios (2008) and Sotani (2009) for TeVeS also hold for Gen-TeV_S.

4) Result is **NOT** generalizable. Easy to prove that rotating or time dependent spacetimes will look different in two theories ($K_2 \neq 0$)

What do **black holes** look like in Generalized TeVeS?

Assumptions:

- ✓ Static and spherically symmetric
- ✓ Only non-zero term of vector field is time component
 - ✓ Only subset of possible solutions
 - ✓ Effect of radial component has not been studied

Vacuum Spacetimes: black holes and naked singularities

Giannios (2005), Sagi & Bekenstein (2008), PL (in prep.)

$$d\tilde{s}^2 = \left(\frac{1 - r_c/r}{1 + r_c/r} \right)^a dt^2 + \left(1 + \frac{r_c}{r} \right)^{2+a} \left(1 - \frac{r_c}{r} \right)^{2-a} (dr^2 + r^2 d\Omega^2)$$

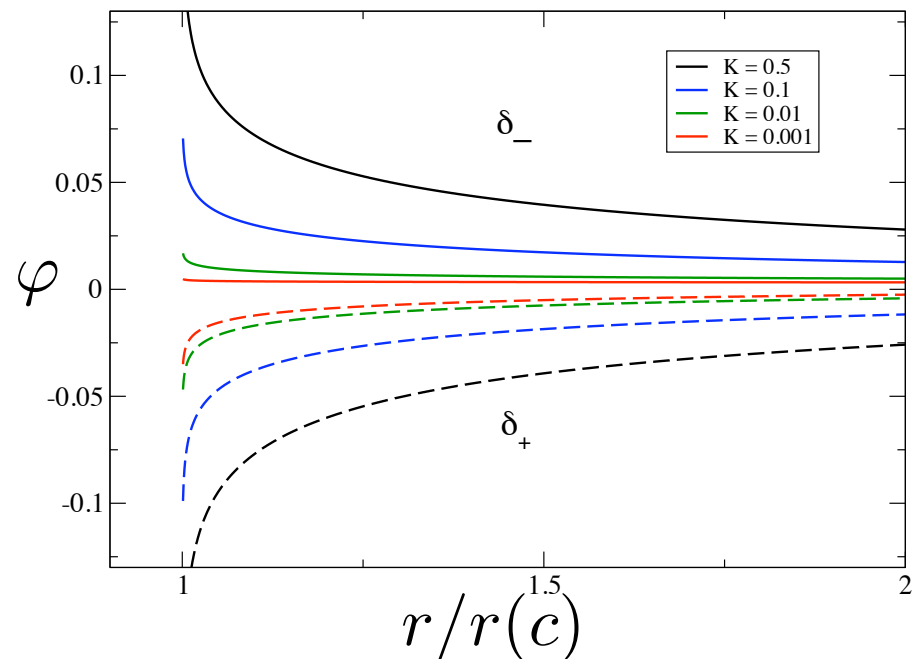
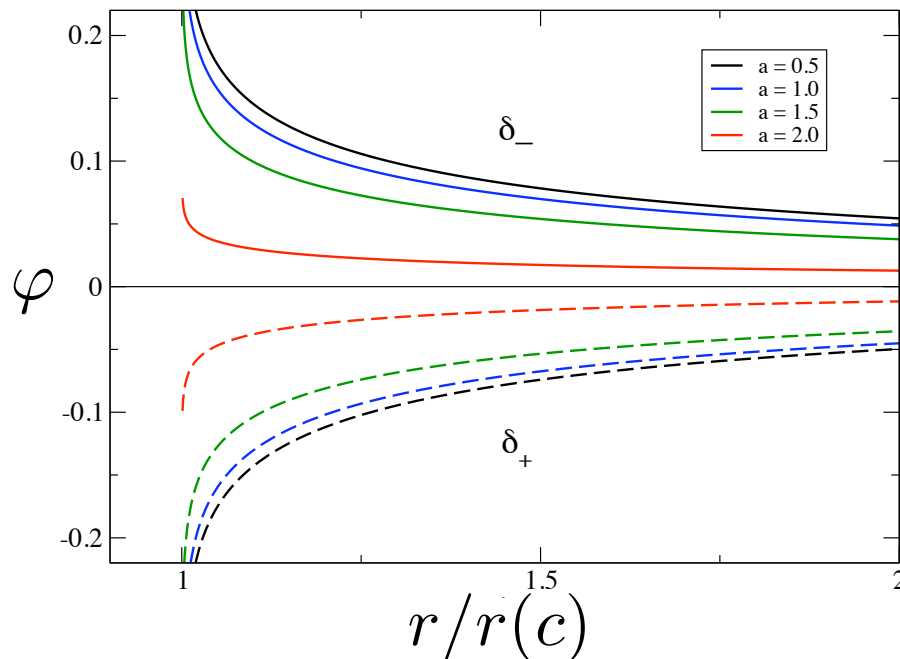
- ✓ ‘a’ is extra free parameter relating to “scalar mass” of the black hole.
- ✓ Solution is actually **identical** to a subset of the **Brans-Dicke type I solutions**
 - ✓ **a = 2** is **only black hole** solution - **identical to GR-Schwarzschild solution!**
 - ✓ **0 < a < 2** and **2 < a < 4** are **naked singularities**
 - ✓ **a > 4** have non-essential singularity, but divergent surface area.

Vacuum Spacetimes: black holes and naked singularities

Giannios (2005), Sagi & Bekenstein (2008), PL (in prep.)

$$d\tilde{s}^2 = \left(\frac{1 - r_c/r}{1 + r_c/r} \right)^a dt^2 + \left(1 + \frac{r_c}{r} \right)^{2+a} \left(1 - \frac{r_c}{r} \right)^{2-a} (dr^2 + r^2 d\Omega^2)$$

✓ Actually 2 “background” solutions which give same physical metric. These will give different perturbations, etc.



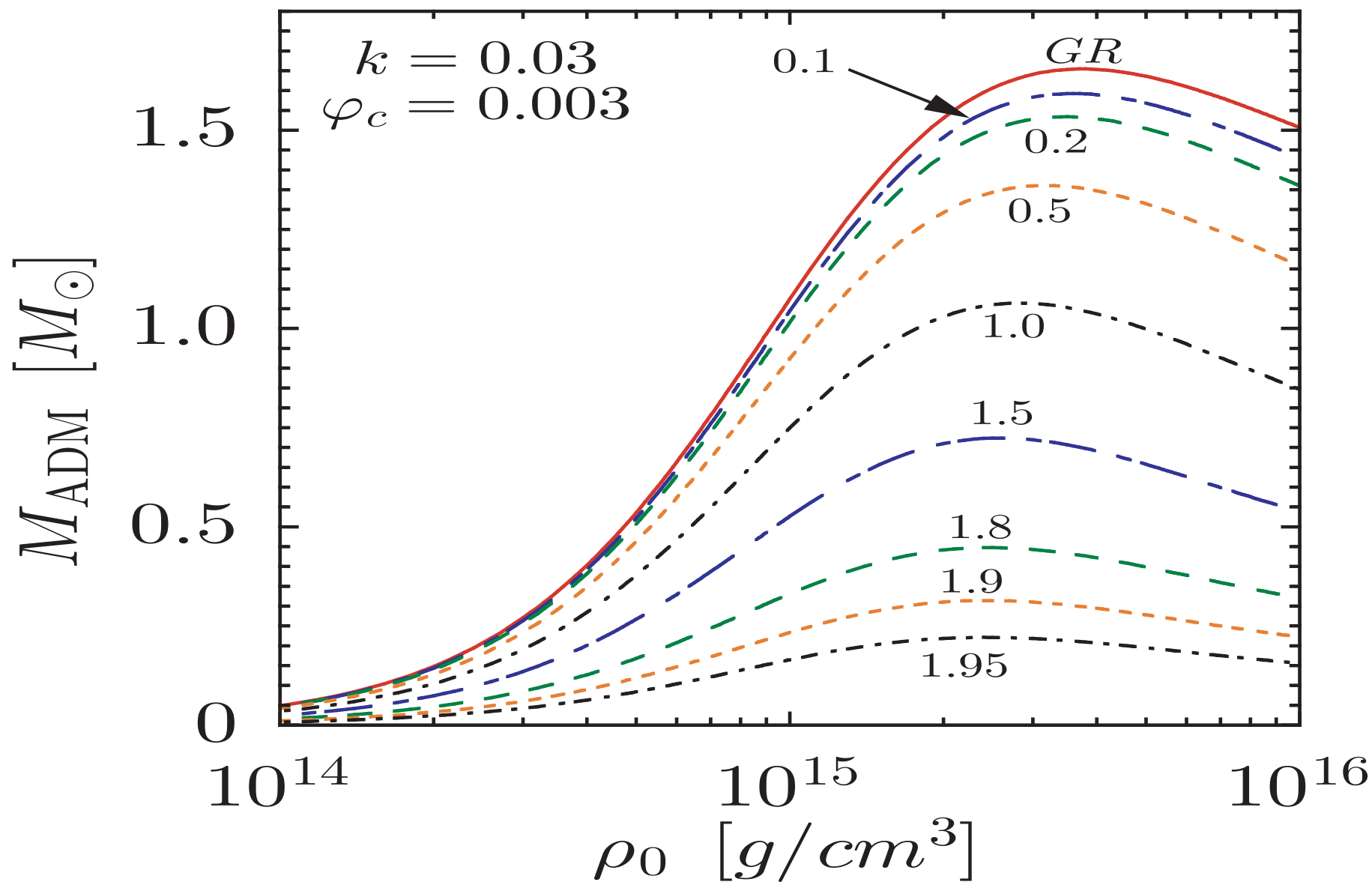
What do neutron stars look like in Generalized TeVeS?

Assumptions:

- ✓ Static and spherically symmetric
- ✓ Only non-zero term of vector field is time component
 - ✓ Only subset of possible solutions
 - ✓ Effect of radial component has not been studied
- ✓ For Neutron star assumed perfect fluid

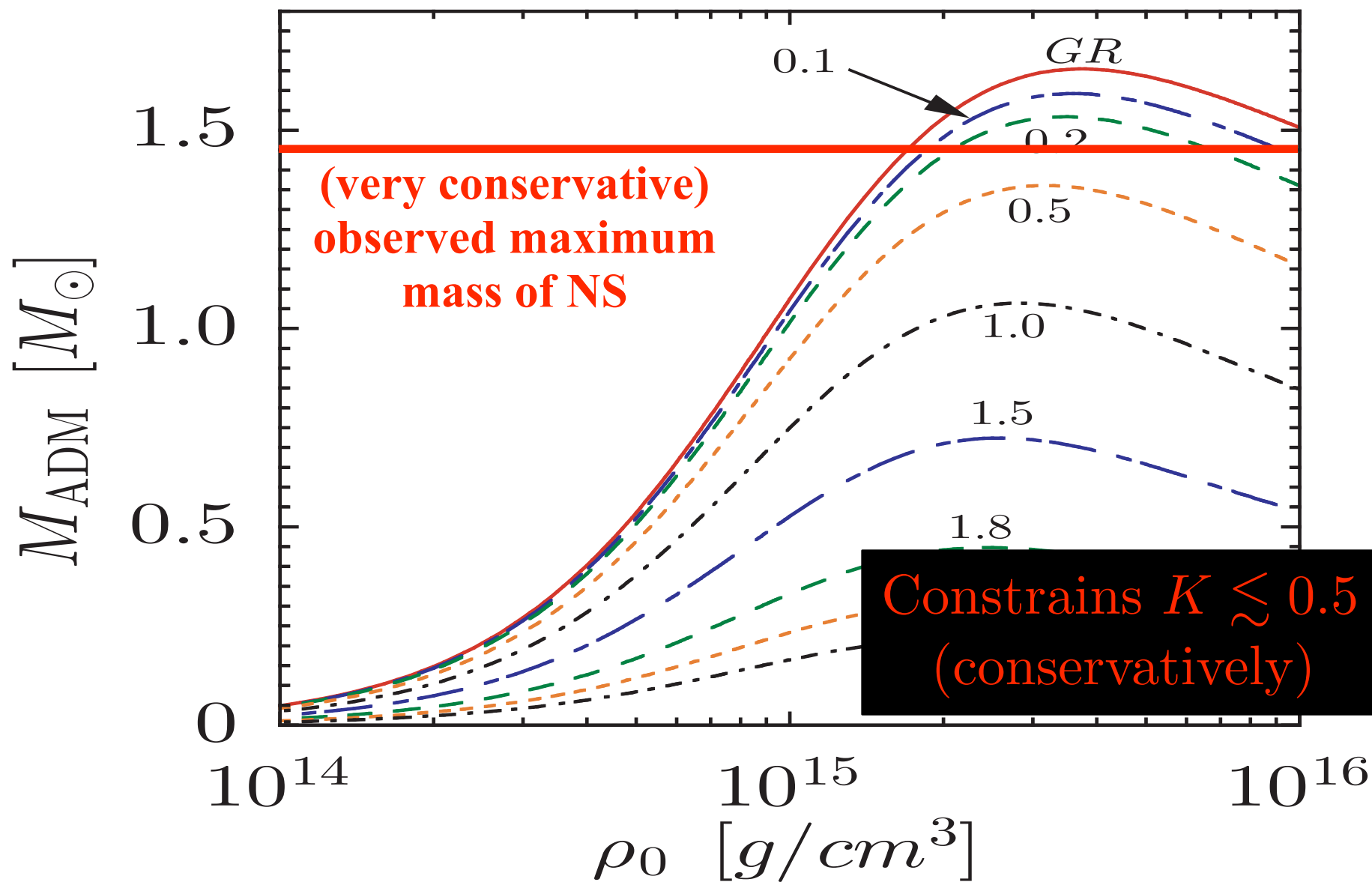
Neutron Stars in Generalized TeVeS

PL, Sotani & Giannios (2008), PL (2009)



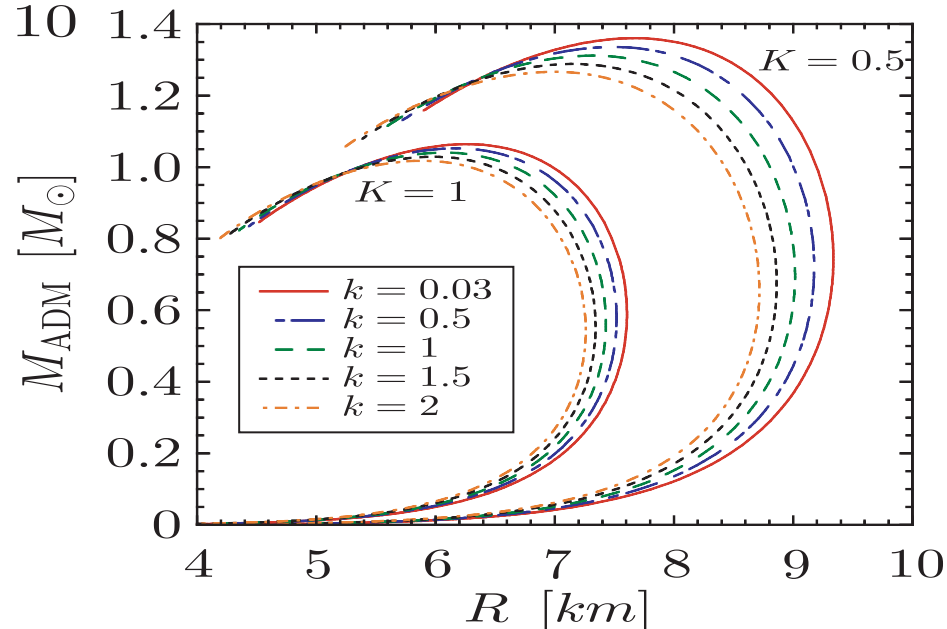
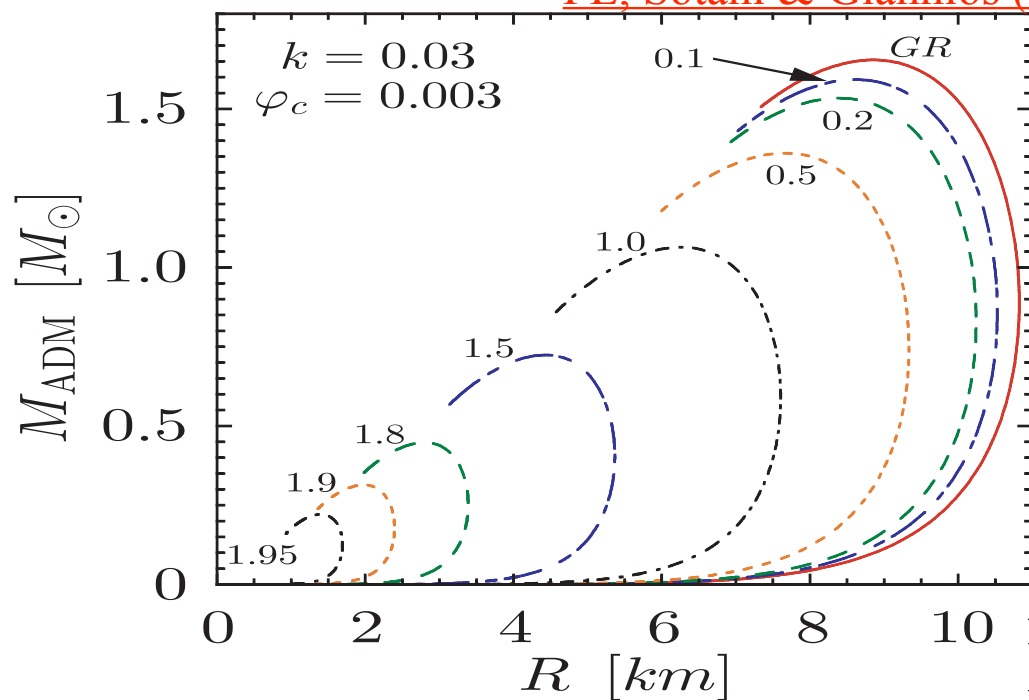
Neutron Stars in Generalized TeVeS

PL, Sotani & Giannios (2008), PL (2009)



Neutron Stars in Generalized TeVeS

PL, Sotani & Giannios (2008), PL (2009)



Conclusions

- ✓ Generalized TeVeS still a viable theory in the strong-field regime
- ✓ Can utilise NS observations to restrict parameter space of theory
- ✓ Vacuum spacetimes can have different structure to GR, but also admit Schwarzschild as a solution.
- ✓ Many open questions for vacuum spacetimes;
 - ✓ **Does gravitational collapse lead to naked singularities or black holes?**
 - ✓ **Are such objects stable?**
 - ✓ **What is the structure of rotating BHs?**
 - ✓ **Many questions to do with gravitational wave emission**
 - ✓ **etc.**

THANK YOU!